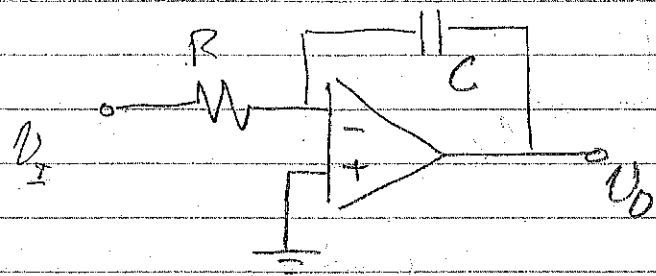


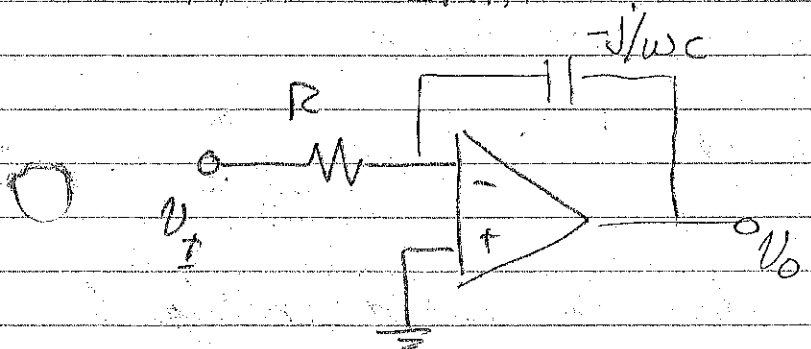
MILLER INTEGRATOR

Consider the following:



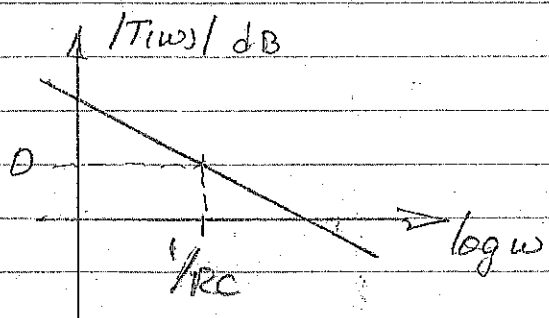
We can look at this circuit in either the time domain or the frequency (phasor) domain.

PHASOR DOMAIN



$$T(\omega) = \frac{+j/\omega C}{R} = -\frac{1}{j\omega RC}$$

A Bode plot looks like this:

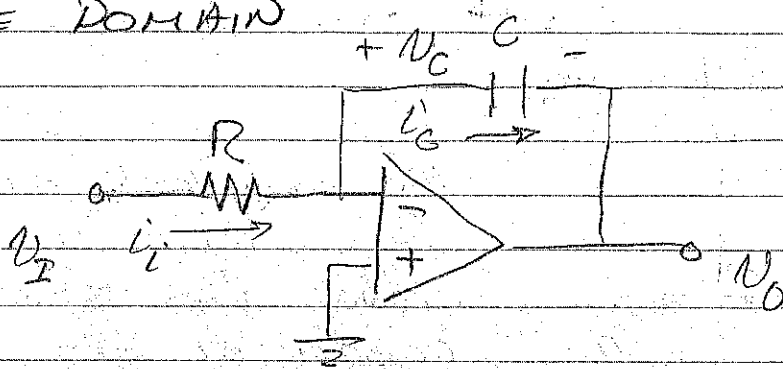


pole at $\omega = 0$

Also $\angle T(\omega) = 90^\circ$

So this is a low-pass filter, in that frequencies of $\omega \ll 1/RC$ are "passed" whereas those above are attenuated.

TIME DOMAIN



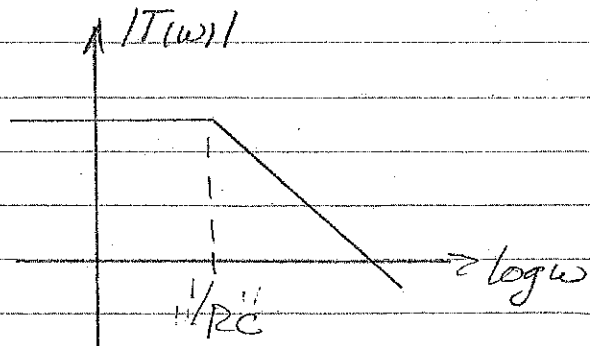
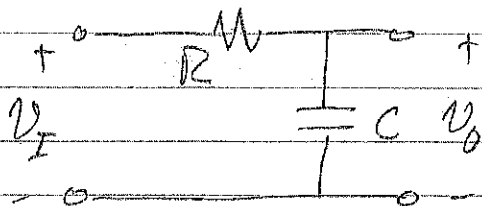
$$i_i = i_c = \frac{V_I}{R} \quad V_o = -V_c = -\frac{1}{C} \int_{t_0}^t \frac{V_I}{R} dt + V_o(t_0)$$

If we take $t_0 = 0$, $V_o(0) = 0$, we have

$$V_o = -\frac{1}{RC} \int_0^t V_I dt$$

So this circuit integrates the input voltage!
This is a MILLER INTEGRATOR.

A simple RC circuit has some connection with this op amp:

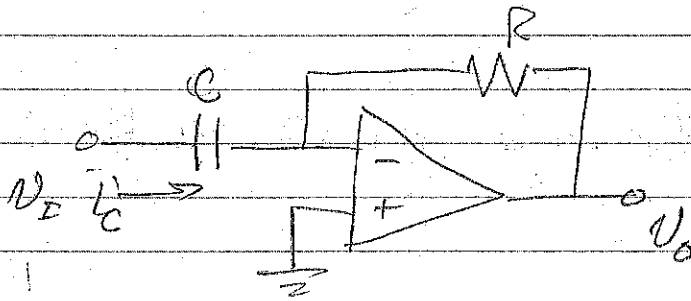


$$T(w) = \frac{1}{1 + jwRC}$$

So the MILLER INTEGRATOR is a low-pass filter with a break point at $\omega = 0$.
Looking from the RC circuit side, we can say that for $\omega \gg 1/RC$, the RC circuit is an integrator (based on the Bode plot).

MILLER DIFFERENTIATOR

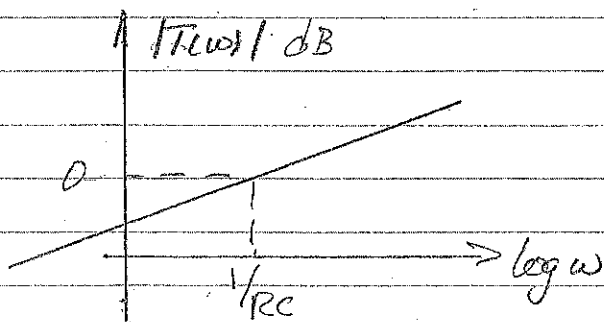
By interchanging R and C, we get a differentiator:



$$i_C = C \frac{dV_i}{dt} \quad V_o = -i_C R = -RC \frac{dV_i}{dt}$$

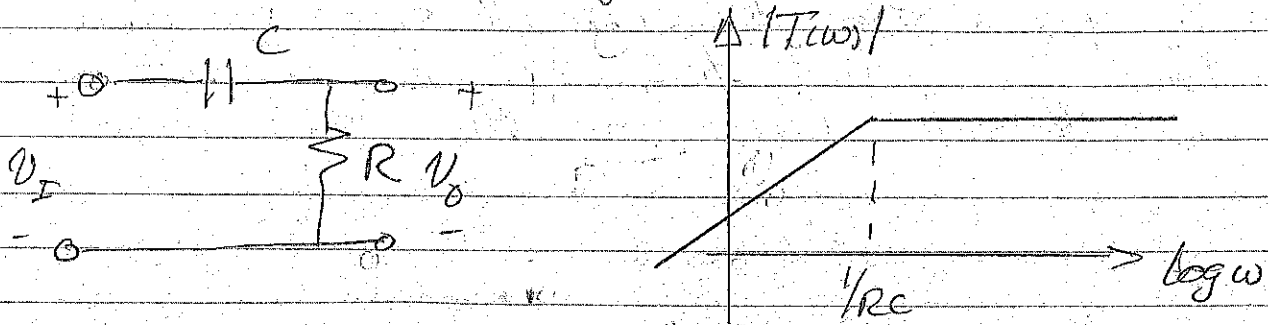
The phasor domain solution is

$$T(\omega) = -j\omega RC$$



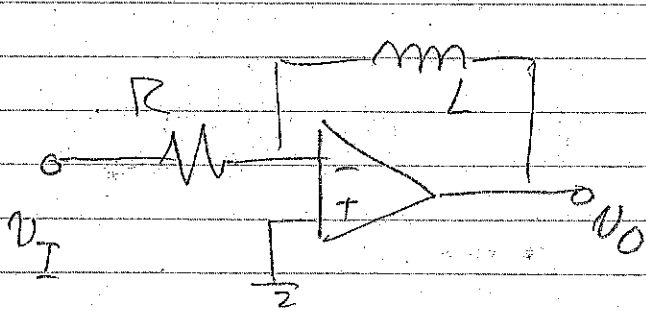
$$\text{and } \angle T(\omega) = -90^\circ$$

This is a high-pass filter. The RC circuit analog is

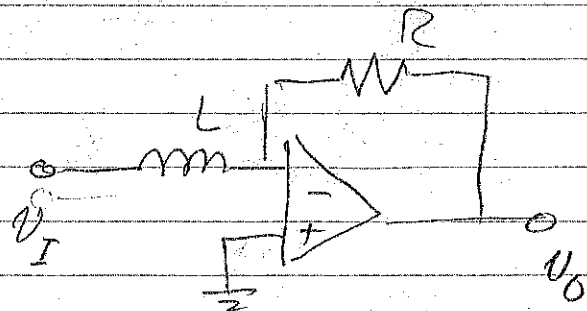


This has the same frequency response as the differentiator if $\omega \ll 1/RC$.

We can integrate and differentiate with inductors:



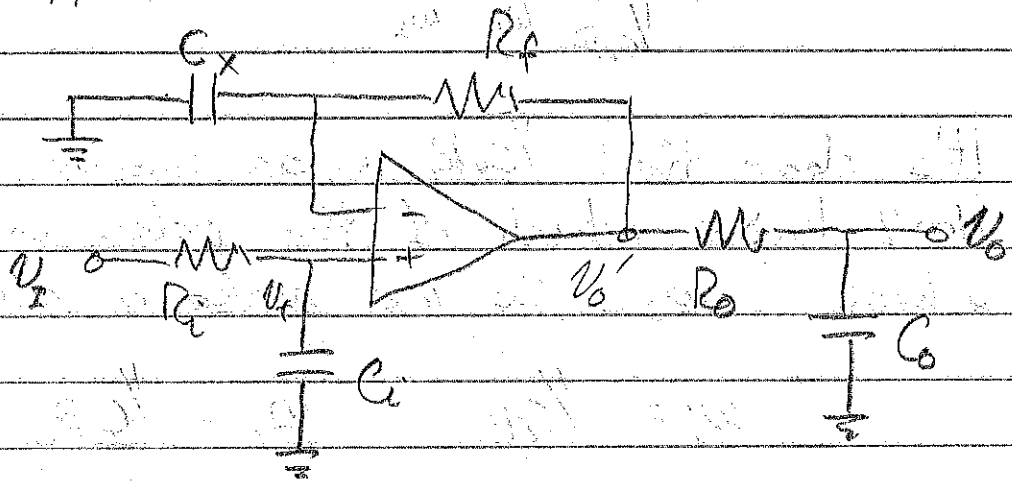
DIFFERENTIATOR



INTEGRATOR

The circuit below is intended to be a band-pass filter. Choose resistor and capacitor values so that

- the 3dB bandwidth is 20 krad/s.
- the upper breakpoint is 80 krad/s



Non-inverting configuration:

$$V_o' = V_+ (1 + j\omega C_x R_f)$$

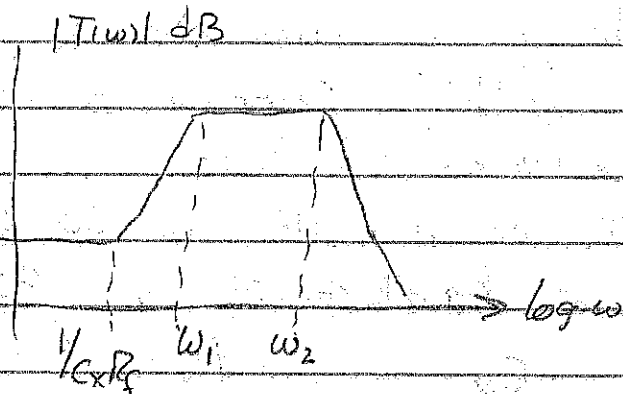
$$V_+ = V_i \frac{1}{1 + j\omega C_i R_i}$$

$$V_o = V_o' \frac{1/j\omega C_o}{1/j\omega C_o + R_o} = V_o' \frac{1}{1 + j\omega C_o R_o}$$

From this we have

$$T(\omega) = \frac{V_o}{V_i} = \frac{(1 + j\omega C_x R_f)}{(1 + j\omega C_o R_o)(1 + j\omega C_i R_i)}$$

We have a zero and two poles, so...



It's clear that $1/C_i R_i$ is as shown, but we don't know which of the poles is ω_1 , and which is ω_2 . So we make a choice:

$$\omega_1 = 1/C_i R_i \quad \omega_2 = 1/C_o R_o$$

We also have $\omega_2 = 80 \frac{\text{krad}}{\text{s}}$

and $\omega_2 - \omega_1 = 20 \frac{\text{krad}}{\text{s}} \Rightarrow \omega_1 = 60 \text{ krad/s}$

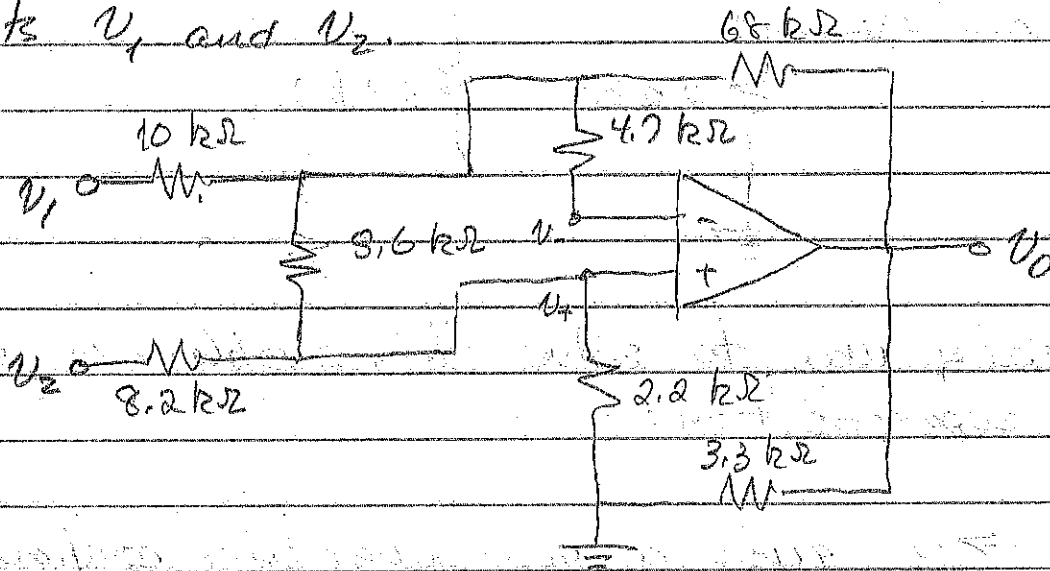
We now need to choose R 's and C 's, but we have no specifications so we pick something for the resistors:

$$R_i = 1 \text{ k}\Omega \Rightarrow C_i = \frac{1}{\omega_1 R_i} = 16.7 \text{ nF}$$

$$R_o = 1 \text{ k}\Omega \Rightarrow C_o = \frac{1}{\omega_2 R_o} = 12.5 \text{ nF}$$

Quiz 3 Fall 2000

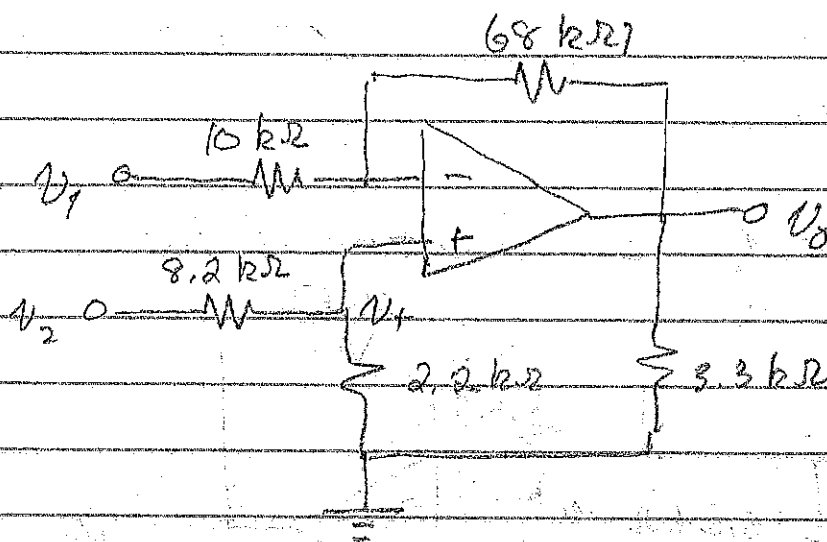
Find the output V_o as a function of the inputs V_1 and V_2 .



We can simplify a bit here... Since we have negative feedback, $V_+ = V_-$. Also, there is no current in the $4.7 \text{ k}\Omega$ resistor, so that can be replaced by a short, in which case there's no voltage across $5.6 \text{ k}\Omega$, and we can open circuit that!

We have re-drawn the circuit, incorporating these changes, on the next page.

We have left the $3.3 \text{ k}\Omega$ resistor in place, but it should be clear that V_o is not affected by it (because the op amp output resistance is zero).



An easy way to solve this problem is to use superposition:

$V_1 \rightarrow 0$ gives a non-inverting configuration, with

$$V_+ = V_2 \cdot \frac{2.2}{2.2 + 8.2} = 0.21 V_2$$

Then $V_0^{NI} = V_+ \left(1 + \frac{68}{10}\right) = 7.8 V_+ = 1.64 V_2$.

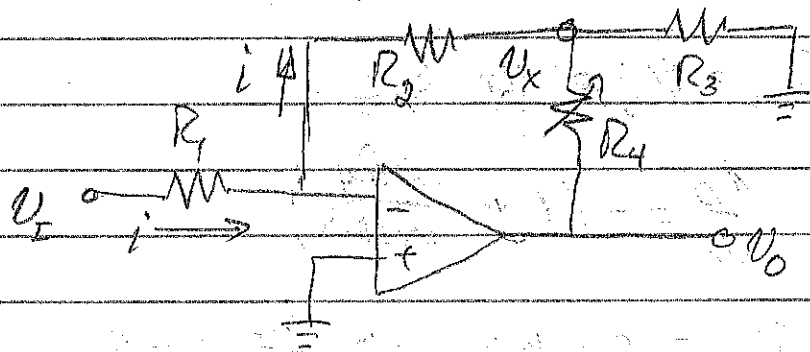
With $V_2 \rightarrow 0$ we have an inverting configuration.

$$V_0^I = -\frac{68}{10} V_1 = -6.8 V_1$$

So $V_0 = V_0^I + V_0^{NI} = -6.8 V_1 + 1.64 V_2$

Choose values for R_1, R_2, R_3 and a range for R_4 so that

- the input resistance seen by the source is 100 k Ω
- the gain V_o/V_i varies between -2 and -5.



Let's find V_o/V_i in terms of R 's ...

$$\frac{V_x - V_o}{R_4} + \frac{V_x}{R_2} + \frac{V_x}{R_3} = 0$$

This gives V_o in terms of V_x :

$$V_o = V_x R_4 \left(\frac{1}{R_2} + \frac{1}{R_3} + \frac{1}{R_4} \right)$$

So we need V_x in terms of V_i :

$$V_x = -i R_2 = -\frac{V_i}{R_1} R_2$$

Substituting that above gives $\frac{V_o}{V_i} = -\frac{R_2}{R_1} \left(\frac{R_4}{R_2} + \frac{R_4}{R_3} + 1 \right)$

P6b

$$\frac{V_0}{V_I} = -\frac{R_2}{R_1} \left(1 + \frac{R_{T1}}{R_3} + \frac{R_{T1}}{R_2} \right)$$

To get the required R_{in} we need $R_1 = 100 \text{ k}\Omega$.
There are a lot of choices for the other resistors, so let's choose something:

$$R_2 = R_3 = 100 \text{ k}\Omega$$

$$\Rightarrow \frac{V_0}{V_I} = - \left(1 + \frac{2R_{T1}}{100 \text{ k}\Omega} \right)$$

$$\text{Now } R_{T1} = 50 \text{ k}\Omega \Rightarrow \frac{V_0}{V_I} = -2$$

$$R_{T1} = 200 \text{ k}\Omega \Rightarrow \frac{V_0}{V_I} = -5$$

So the range for R_{T1} is

$$50 \text{ k}\Omega \leq R_{T1} \leq 200 \text{ k}\Omega$$

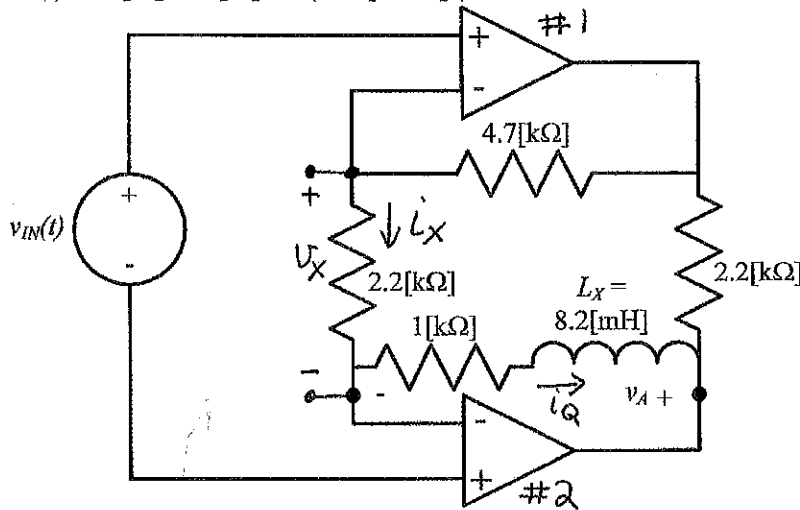
2. {45 Points} Use the circuit below to solve this problem. Assume an ideal op amp.

a) Find the voltage gain V_A / V_{IN} .

b) Find the voltage gain V_a / V_{in} as a function of angular frequency.

c) Find the voltage gain v_a / v_{in} as a function of time, if

$$v_{IN}(t) = 6[V] + 3[V]\cos(300[\text{rad/s}]t).$$



Op amp #1
has neg. fdbk,
through 4.7[kΩ].

Op amp #2
has neg. fdbk,
through L_X and
1[kΩ] resistor.

So, by KVL, $V_X = V_{IN}$.

$$i_X = \frac{V_X}{2.2[\text{k}\Omega]} = \frac{V_{IN}}{2.2[\text{k}\Omega]} = i_Q$$

a) $\frac{V_A}{V_{IN}} = ?$

Now @ dc, L_X acts as a
short circuit, so

$$V_A = -i_Q 1[\text{k}\Omega] = -\frac{V_{IN}}{2.2[\text{k}\Omega]} 1[\text{k}\Omega]$$

$$\frac{V_A}{V_{IN}} = -\frac{1}{2.2} = \boxed{-0.455}$$

see next page

b) $\frac{V_a}{V_{in}} = ?$ In the phasor domain,

$$V_a = -I_q (1 \text{ [k}\Omega\text{]} + j\omega 8.2 \text{ [mH]})$$

$$V_a = -\frac{V_{in}}{2.2 \text{ [k}\Omega\text{]}} (1 \text{ [k}\Omega\text{]} + j\omega 8.2 \text{ [mH]})$$

$$\frac{V_a}{V_{in}} = -0.455 - j\omega (3.727) \left[\frac{\mu\text{H}}{\Omega} \right]$$

Now, we remember that $1 \text{ [H]} = 1 \frac{\text{[V][s]}}{\text{[A]}}$,
so $1 \left[\frac{\text{H}}{\Omega} \right] = 1 \text{ [s]}$.

$$\boxed{\frac{V_a}{V_{in}} = -0.455 - j\omega 3.727 \text{ [\mu s]}}$$

c) $\frac{V_a}{V_{in}} = ?$ Since these are signal quantities,
 $V_{in} = 3 \text{ [V]} \cos(300 \left[\frac{\text{rad}}{\text{s}} \right] t)$

$$V_a(t) = -i_q (1 \text{ [k}\Omega\text{]} + 8.2 \text{ [mH]}) \frac{d i_q}{dt}$$

$$\text{Since } i_q = \frac{3 \text{ [V]} \cos(300 \left[\frac{\text{rad}}{\text{s}} \right] t)}{2.2 \text{ [k}\Omega\text{]}} = 1.364 \text{ [mA]} \cos 300 \left[\frac{\text{rad}}{\text{s}} \right] t$$

$$V_a(t) = -1.364 \text{ [V]} \cos(300 \left[\frac{\text{rad}}{\text{s}} \right] t) +$$

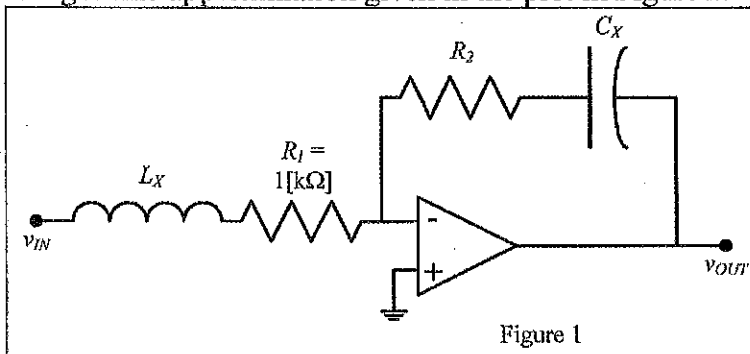
$$-11.18 \left[\frac{\mu\text{H}}{\text{A}} \right] 300 \left[\frac{\text{rad}}{\text{s}} \right] (-\sin(300 \left[\frac{\text{rad}}{\text{s}} \right] t))$$

see next page

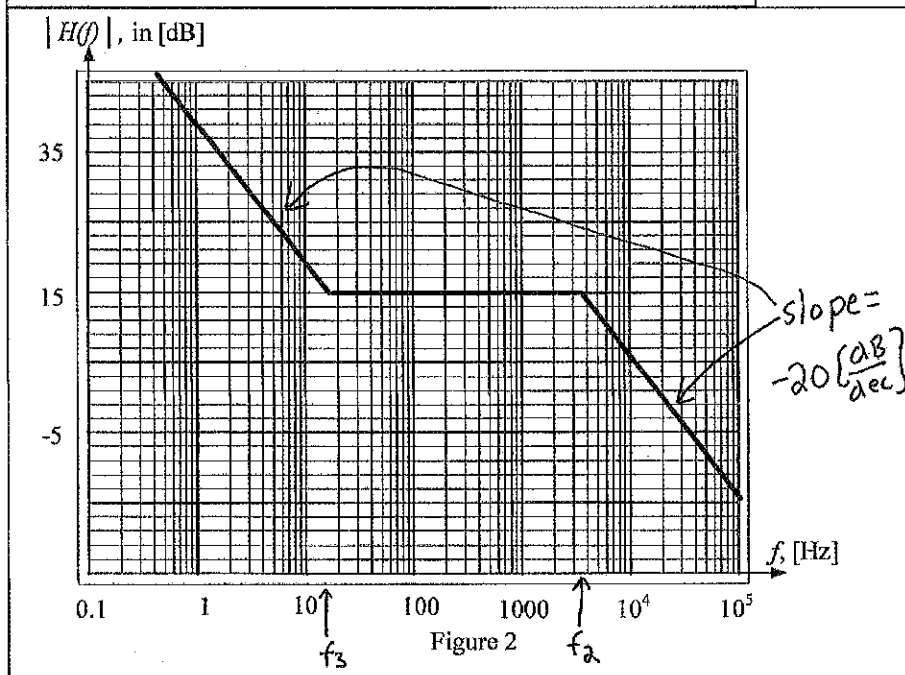
$$\text{So, } \frac{V_a}{V_{in}} = -\left(\frac{1.364}{3}\right) + 1.118 \frac{\sin\left(300\left\{\frac{\text{rad}}{\text{s}}\right\}t\right)}{\cos\left(300\left\{\frac{\text{rad}}{\text{s}}\right\}t\right)} \times 10^{-3}$$

$$\frac{V_a}{V_{in}} = -0.455 + 0.001118 \tan\left(300\left\{\frac{\text{rad}}{\text{s}}\right\}t\right)$$

3. {45 Points} Assume an ideal op amp in the schematic in Figure 1. Find the values of R_2 , C_x , and L_x that will produce the magnitude Bode plot that has the straight-line approximation given in the plot in Figure 2.



← This is the inverting configuration of the op amp, and so we know the gain. By going to the phasor domain, we can get the transfer function.



The transfer function,
$$\frac{V_{out}}{V_{in}} = \frac{-(R_2 + \frac{1}{j\omega C_x})}{R_1 + j\omega L_x} =$$

$$H(\omega) = \frac{-(j\omega C_x R_2 + 1)}{j\omega C_x (R_1 + j\omega L_x)}$$

See next page

This has 2 poles, and 1 zero.

One pole is at $\omega_1 = 0$

and one at $\omega_2 = \frac{R_1}{L_x}$

The zero is at $\omega_3 = \frac{1}{R_2 C_x}$

The pole is at $f_2 = 3,500 \text{ [Hz]}$, which

corresponds to $\omega_2 = 2\pi f_2 = 22.0 \text{ [krad/s]}$

$$22.0 \text{ [krad/s]} = \frac{1 \text{ [k}\Omega]}{L_x}, \text{ so}$$

$$L_x = 45 \text{ [mH]}$$

In the frequency range below f_2 (and ω_2),

$|R_1| > |j\omega L_x|$, so we can neglect L_x .

In a similar way, above f_3 (and ω_3),

$|R_2| > \left| \frac{1}{j\omega C_x} \right|$, so we can neglect C_x .

So, between f_3 and f_2 , the gain is $-\frac{R_2}{R_1}$,

and $20 \log_{10} \left| \frac{R_2}{R_1} \right| = 15 \text{ [dB]}$.

$$10^{(15/20)} = \frac{R_2}{R_1} = 5.62, \text{ so } R_2 = 5.62 \text{ [k}\Omega]$$

(see next page)

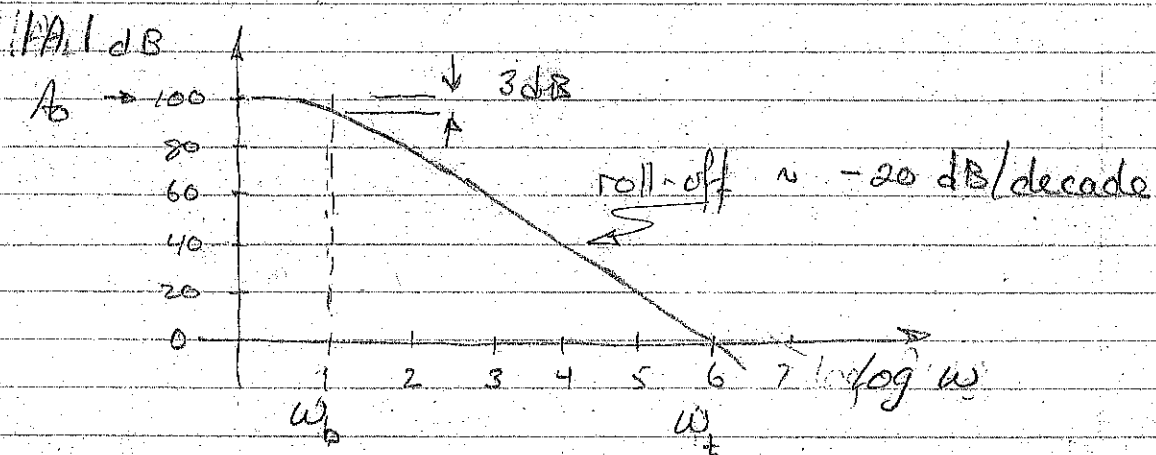
The zero is at $f_3 = 15 \text{ [Hz]}$, so

$$\omega_3 = 2\pi 15 = 94.2 \left[\frac{\text{rad}}{\text{s}} \right] = \frac{1}{R_2 C_x}$$

$$C_x = \frac{1}{(94.2)(5620)} = \boxed{1.89 \text{ [}\mu\text{F]}}$$

NONIDEAL PERFORMANCE OF OP AMPS

We have been assuming that the open-loop gain A_o is large (∞) and constant with frequency. In fact its behavior in typical op-amps is as follows:



3 dB frequency $\equiv \omega_b$

Generally we have

$$A_i(\omega) = \frac{A_o}{1 + j\omega/\omega_b}$$

which for high frequencies is

$$A_i(\omega) \approx \frac{A_o \omega_b}{j\omega} \quad (\omega \rightarrow \infty)$$

$$\text{Now } |A(\omega)| \rightarrow 1 \Rightarrow \omega \rightarrow \omega_t = A_o \omega_b$$

where ω_t is the UNITY GAIN BANDWIDTH.

So we have $A(\omega) \approx \frac{W_t}{j\omega}$

and $|A(\omega)| \approx W_t/\omega$

Op amp data sheets generally specify W_t so we can easily estimate the open loop gain as a fn of frequency.

INVERTING CONFIGURATION REVISITED

For noninfinite open loop gain we had

$$\frac{V_o}{V_i} = \frac{-R_2/R_1}{1 + (1 + R_2/R_1)/A}$$

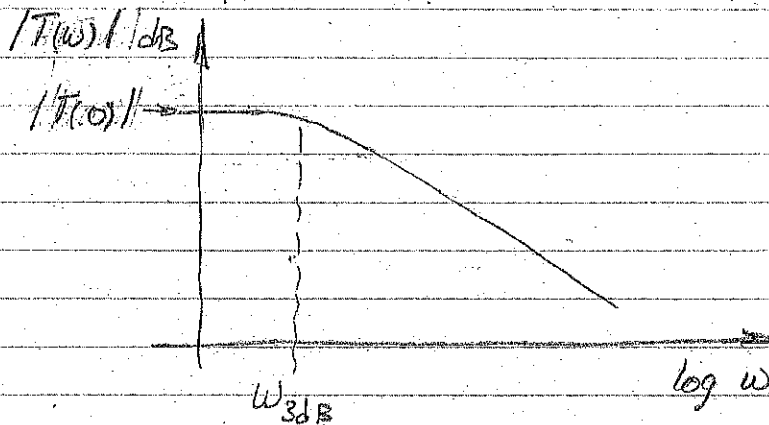
Substituting $A(\omega) = \frac{A_0}{1 + j\omega/\omega_b}$ gives

$$\frac{\overline{V_o(\omega)}}{\overline{V_i(\omega)}} = \frac{-R_2/R_1}{1 + (1 + R_2/R_1)/A_0 + \frac{j\omega}{W_t/(1 + R_2/R_1)}}$$

and if $A_0 \gg 1 + R_2/R_1$ we can simplify to

$$T(\omega) = \frac{\overline{V_o(\omega)}}{\overline{V_i(\omega)}} = \frac{-R_2/R_1}{1 + \frac{j\omega}{W_t/(1 + R_2/R_1)}}$$

Thus the inverting configuration has a magnitude bode plot that looks like...



where $w_{3dB} = \frac{w_t}{1 + R_2/R_1}$

and $w \rightarrow 0 \Rightarrow |T(0)| \rightarrow 1 + R_2/R_1$

NON-INVERTING CONFIGURATION

Analysis of the noninverting configuration shows that

$$T(w) = \frac{V_o(w)}{V_i(w)} = \frac{1 + R_2/R_1}{1 + \frac{jw}{w_t(1 + R_2/R_1)}}$$

So $w_{3dB} = \frac{w_t}{1 + R_2/R_1}$ and $|T(0)| = 1 + R_2/R_1$

So the GAIN - BANDWIDTH PRODUCT; K_{GB}

is $|T(0)| \cdot w_{3dB} = w_t$ is CONSTANT.

This is also approximately true for the inverting configuration.

Thus we have a fundamental trade-off between gain and bandwidth (i.e. the frequency range over which the gain is constant).

SLEW RATE

In addition to ω -dependent gain, real op amps can provide output voltages that change at a finite maximum rate. The max rate is the SLEW RATE SR:

$$SR = \left. \frac{dV_o}{dt} \right|_{\max}$$

SEDRA & SMITH, FIG. 2.43

Note that a finite slew rate is not the same thing as limited frequency response. For ω -dependent gain, the output amplitude will be reduced, but V_o is still a good representation of the input signal. In other words, the amp response is still linear.

However, a finite slew rate can change the shape of the output, so the amp is no longer linear. For example, a sinusoid has a varying slope, which maximizes at the zero-crossings, and will be distorted by finite slew rate.

SEDRA & SMITH FIG. 2.44

Specification: FULL-POWER BANDWIDTH f_M :

$$\omega_M V_{o\max} = SR$$

$$\Rightarrow f_M = \frac{SR}{2\pi V_{o\max}}$$

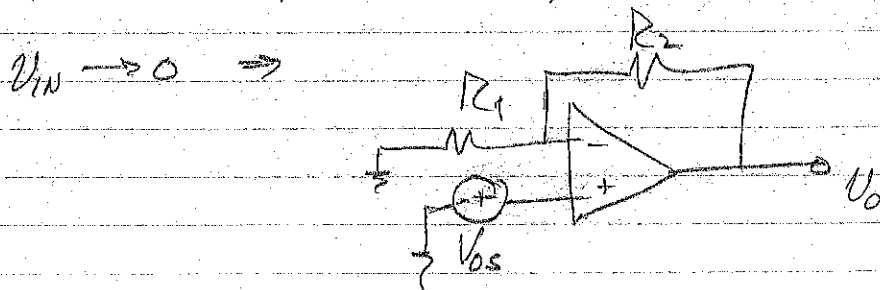
V_{omax} is the rated max output voltage,
and f_m is the frequency at which
a sinusoid of amplitude V_{omax} will begin
to distort.

Smaller amplitude sinusoids can operate
at higher frequencies before distortion sets in.
For amplitude V_o we have distortion free
output until a frequency ω such that

$$V_o = V_{omax} \frac{\omega M}{\omega}$$

INPUT OFFSET VOLTAGE (V_{os})

For an ideal op amp, $V_1 = V_2 = 0 \Rightarrow V_o = 0$.
 For $V_{os} \neq 0$, $V_1 = V_2 = 0$ gives a non-zero V_o .
 Assuming $V_{os} > 0$, we can analyze the effect of V_{os} on both inverting and non-inverting configurations by shorting the input signal:

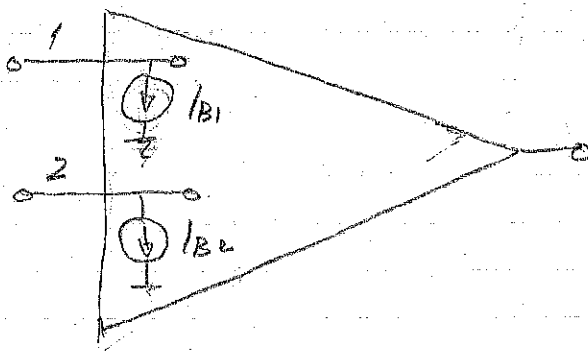


Here $V_o = V_{os} (1 + R_2/R_1)$ which will be superimposed on the output due to V_{in} .

Possible Solution: Some amps are provided with "trim" pins to which a simple circuit can be connected to reduce V_o to 0 for $V_1 = V_2 = 0$.

Another dc-related problem is INPUT BIAS CURRENT.

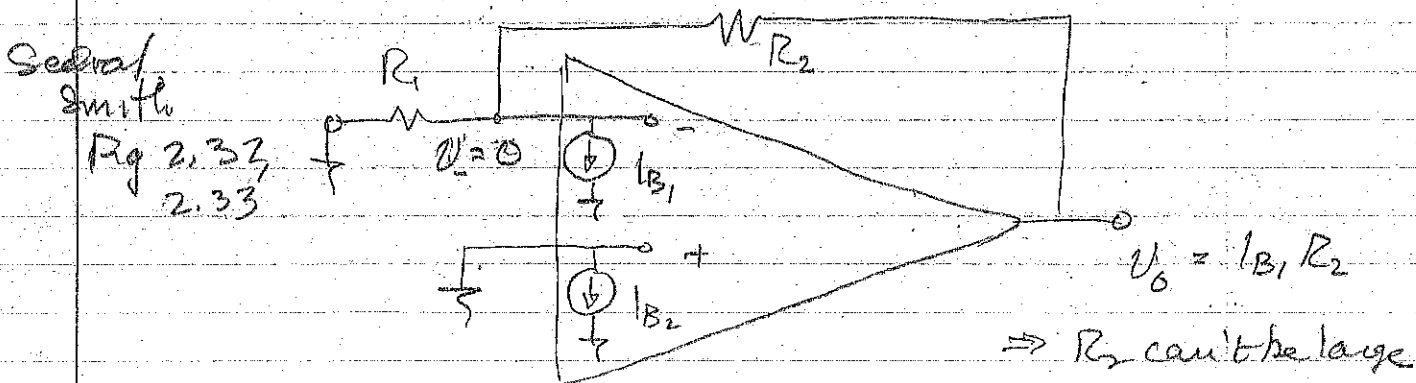
Internal op amp structure results in the following equivalent circuit:



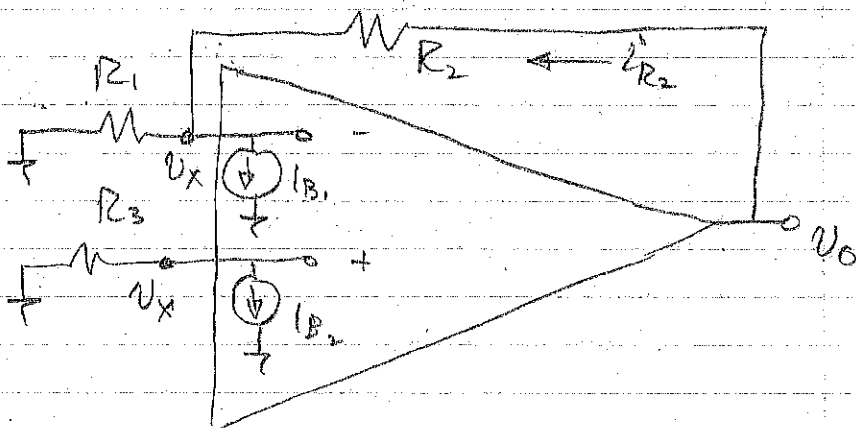
Define INPUT BIAS CURRENT $I_B = \frac{1}{2}(I_{B1} + I_{B2})$

and INPUT OFFSET CURRENT $I_{os} = |I_{B1} - I_{B2}|$

Now for the INVERTING CONFIGURATION:



Compensation: add series R_3 to + input:



$$V_x = -I_{B2} R_3$$

$$I_{R2} = \frac{V_x}{R_1} + I_{B1} = \frac{-I_{B2} R_3}{R_1} + I_{B1}$$

$$V_o - V_x - I_{R2} R_2 = 0$$

$$\therefore V_o = V_x + I_{R2} R_2 = -I_{B2} R_3 + I_{B1} R_2 - \frac{I_{B2} R_2 R_3}{R_1}$$

If $I_{os} = 0$, i.e. $I_{B1} = I_{B2} = I_B$, we have

$$V_o = I_B [R_2 - R_3 (1 + R_2/R_1)]$$

and $V_o = 0$ if $R_3 = R_1 R_2 / (R_1 + R_2)$

If R_3 is chosen as such, and $I_{os} \neq 0$, say $I_{B1} = I_B + I_{os}/2$, $I_{B2} = I_B - I_{os}/2$, we have

$$V_o = I_{os} R_3$$

which is much smaller than w/o R_3 .

General result: To minimize the effect of I_B , place a resistance at the noninverting input equal to the dc resistance seen by the inverting terminal.